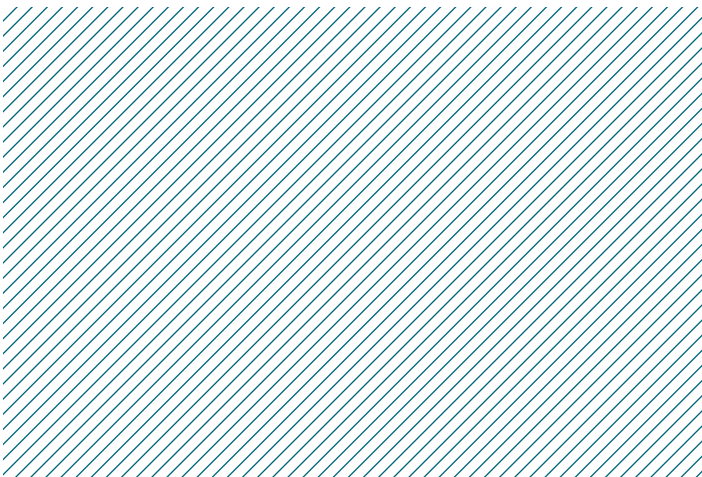




# ImagingRing

Specification sheet



System	ImagingRing m
<b>Mounting</b>	medPhoton robotic platform
<b>Benefits</b>	✓ Flexibility
	✓ Ultra-large gantry bore (121 cm) for extra-large field-of-view (FOV)
	✓ IORT, Brachytherapy, IGRT (particle), interventional radiology, surgical
	✓ Battery powered maneuverability
	✓ Wireless remote control
	✓ Robotic movements
	✓ Non-isocentric imaging and collimation
	✓ Movable lasers to define scan range and for incision planning
<b>CE</b>	EN ISO 13485, EN ISO 14971, EN 62304, EN 62366, IEC 60601-1, IEC 60601-1-2, IEC 60601-1-3, IEC 60601-1-6, IEC 60601-2-28, IEC 60601-2-43, IEC 60601-2-54, EN 1041:2008, EN ISO 15223-1:2016, ANSI/AAMI ES60601-1, CAN/CSA-C22.2 No. 60601-1

Imaging Capabilities	
<b>Customizable Protocols</b>	✓
<b>Adaptive Protocols</b>	✓
<b>Dynamic Collimation</b>	✓ Asymmetric, 4 independent jaws
<b>Isocentric Imaging</b>	✓
<b>Non-Isocentric Imaging</b>	✓

2D imaging	
<b>2D Single Images</b>	✓
<b>2D FOV (in Isocentre) [cm]</b>	25.4 x 25.4
<b>2D Extended FOV (in isocentre) [cm]</b>	25.4 x 65 (optional)
<b>Scout View (Topogram)</b>	✓ (optional)
<b>2D Fluoroscopy (Radioscopy)</b>	✓ (optional)
<b>2D Scatter Correction</b>	✓

3D imaging	
<b>CBCT</b>	✓
<b>Full Scan (360°)</b>	✓
<b>Short Scan (180° + field divergency)</b>	✓
<b>Dual Short Scan (2x180°)</b>	✓ (optional)
<b>CBCT Acquisition Time Full Scan 360°</b>	~ 60 s / 360° @ 7°/s
<b>CBCT Acquisition Time Short Scan</b>	~ 22 s (isocentric short scan 180° + field divergency)
<b>Real Time Reconstruction (inline)</b>	✓ (+60 s for iterative recon. and MAR)
<b>3D Field of View [cm]</b>	Depends on non-isocentric offset from gantry center. All variable sizes of non-circular (elliptic) trans-axial FOVs are individually adjustable per patient scan...
<b>LFOV (large field of view) [cm³]</b>	43 x 43 x 25.4 cm³
<b>SFOV (small field of view) [cm³]</b>	25.4 x 25.4 x 25.4 cm³
<b>Spine FOV (spine field of view) [cm³]</b>	12 x 12 x 20 cm³
<b>limFOV (limited field of view) [cm³]</b>	12 x 12 x 12 cm³
<b>miniFOV (mini field of view) [cm]</b>	6 x 6 x 6 cm
<b>USFOV (ultra-small field of view) [cm]</b>	3 x 3 x 3 cm
<b>3D Limited Field of View (Dynamic Collimation)</b>	✓

Advanced 3D Imaging Features	
CT Mode (fan beam collimation - scatter reduction)	✓
Tomosynthesis	✓

Imaging Geometry	
Source Axis Distance (SAD) [cm]	74.25
Detector Axis Distance (DAD) [cm]	51.7
Source Detector Distance (SDD) [cm]	126 (opposing)
Patient Entrance Reference Point	Isocenter (due to non-isocentric options)

X-Ray System	
Fluoroscopy (Pulsed and Continuous)	✓
Last Image Hold	✓
Frame Integration	✓ (programmable averaging time)
Pulsed Mode	✓ Pulse length typical 10 ms, range 2 – 35 ms @ 12 Hz (2D and 3D)
Continuous Mode	✓ (2D and 3D)
Snapshot Mode	✓
Cine Mode	✓
Dose Modulation During Acquisition	✓ (by velocity modulation optional)
Bow-Tie Filter	✓ (optional) 1 motorized bow-tie filter with 0.3 mm Cu optimized for pelvis configuration
Fixed Filtration	4.4 mm Al eq. @75 kVp
Additional Filtration	<b>Variable filter wheel position for:</b> - 0.5 mm Cu (13.0 mm Al eq. @75 kVp) - 1.5 mm Al - no additional filtration - 0.2 mm Cu (5.2 mm Al eq. @75 kVp) <b>Variable filter carriage position for:</b> - no additional filtration - 1.5 mm Cu (31.3 mm Al eq. @75 kVp)
Cooling System/ Features	Dielectric oil - fan assisted control (no turbulent air flow in surgical environment)

X-ray Tube Anode	
Type	IAE RTM 780H 0.3/0.6
Maximum Output [kW]	Small focus: 6kW Large focus: 25 kW max (typical < 2 kW)
Heat Capacity Anode [kJ]	225
Heat Capacity System [kJ]	X-ray: 610; Total: 910
Cooling Anode [W]	750
Cooling System [W]	75
Focal Spot Size [mm]	0.3/0.6 mm depending on preset (both focal spots available in radiographic and fluoroscopic imaging)
X-ray Primary Aperture [degrees]	55 (asymmetrical)
Anode Angle	10° (the effective emission angle may be larger due to the mounting angle of the X-ray housing)
Tube power rating (kW@100 kVp)	max. 5.2 kW (Small focus), 22 kW (Large focus) (typical < 2 kW)
Frequency [Hz]	1–30 (typical 12)

X-ray Generator	
Type	IMD HF1 GMX-350/S2
Power Rating [kW@100 kVp]	max. 15 kW (typical < 2 kW)
Radiographic Mode	Pulsed or continuous frame averaging
Energy Range [kV]	40–120
Current Range [mA]	Small Focal Spot: 5–30 mA Large Focal Spot: 40–120* mA (* for 2D acquisition)
Automatic Exposure Control (AEC)	Topogram, planar test exposure
Pulse Length [ms]	2–35 (pulsed 12 Hz)
Exposure Time in Fluoroscopic Mode	After 5 min (warning buzzer), max. 10 min in one exposure (regulatory limit)
Voltage range [kV]	40–120
Current range [mA]	0.2–8

Detector System	
Detector Type	Varex XRD4343RF
Scintillator	CsI(Tl)
Panel Size [cm <sup>2</sup> ]	43.2 x 43.2
Flat Panel Resolution	max. 2880 x 2880 @150 µm 1440 x 1440 fast binning mode 960 x 960 ultra fast binning mode
Internal Data Transmission	Glass Fibre

Image Characteristics	
Spatial Resolution (high resolution protocol)	up to 21 LP/cm (in 2 x 2 binning mode and 0° gantry tilt)
Pixel pitch	150 µm physical binned to 300 µm
Matrix	Configurable, user selectable resolution Ultra-Low (243 <sup>3</sup> Voxels) Low (307 <sup>3</sup> Voxels) Medium (386 <sup>3</sup> Voxels) High (487 <sup>3</sup> Voxels) Ultra-High (613 <sup>3</sup> Voxels) (for cubic volume, isotropic resolution)
Voxel Size	Dynamic Voxel size adapted to FOV dimension (ultralow – medium – ultrahigh resolution): LFOV 1.48 - 0.93 - 0.95 mm SFOV 1.05 - 0.66 - 0.41 mm Spine FOV 1.03 - 0.37 - 0.23 mm limFOV 1.03 - 0.35 - 0.20 mm ULFOV 2.25 - 1.41 - 0.89 mm miniFOV 1.03 - 0.35 - 0.12 mm USFOV 1.03 - 0.35 - 0.12 mm
Line pair resolution	tested max. 21 LP/cm (CatPhan) LFOV 3.4 - 5.3 - 8.5 LP/cm SFOV 4.8 - 7.6 - 12.1 LP/cm Spine FOV 4.9 - 13.6 - 21.5 LP/cm limFOV 4.9 - 14.3 - 25.5* LP/cm miniFOV 4.9 - 14.3 - 42.0* LP/cm ULFOV 2.2 - 3.5 - 5.6 LP/cm USFOV 4.9 - 14.3 - 42.0* LP/cm
HU Uniformity (SFOV CBCT phantom conditions)	2%
Geometrical Accuracy	< 0.5 mm (95% confidence interval, gantry inherent deflection compensated) < 1 mm (with external tracking)
Mechanical Flex Correction	✓ 9 + 3 DOF 3 source translations (x, y, z) 3 detector translations (x, y, z) 3 detector rotations (rx, ry, rz) 2 source central axes tilts

Motion	
<b>Wireless System Positioning</b>	✓ (optional - requires HMI)
<b>Wireless Region-of-Interest (ROI) Definition</b>	✓ (optional - requires HMI)
<b>Patient Positioning System (PPS) Compatibility</b>	any
<b>Table Top Indexing</b>	any
<b>Gantry Clearance [cm]</b>	121 (ring bore size), 101.2 (detector)
<b>Gantry Width [cm]</b>	28.5
<b>Travel Range Source [degrees]</b>	683,3 (1.90 turns)
<b>Travel Range Detector</b>	688,54 (1.91 turns)
<b>Max. Rotational Speed [degrees/s] (source, detector)</b>	16°/s, 7°/s typical
<b>Longitudinal Motion Range</b>	Unlimited
<b>Gantry Tilt and Rotation</b>	✓ tilt +90°/ -90° (±30° for 360° CBCT, +60° for short scan CBCT, source below), N x 360° free yaw rotation

Guidance	
<b>Source-sided Trans-axial Lasers (Class 1)</b>	✓ (optional)
<b>Source-sided Motorized Sagittal Lasers (Class 1)</b>	✓ (optional)
<b>Detector-sided Adaptive Lasers (Class 1)</b>	✓ (optional)
<b>Laser Crosshair Mode Pointer Planning</b>	✓ (optional)
<b>Laser Field-size Mode FOV Planning</b>	✓ (optional)
<b>Two Cameras inside gantry (prepared for stereoscopic computer vision applications**)</b>	✓ (optional)
<b>Two Cameras inside detector arm (prepared for stereoscopic computer vision applications**)</b>	✓ (optional)

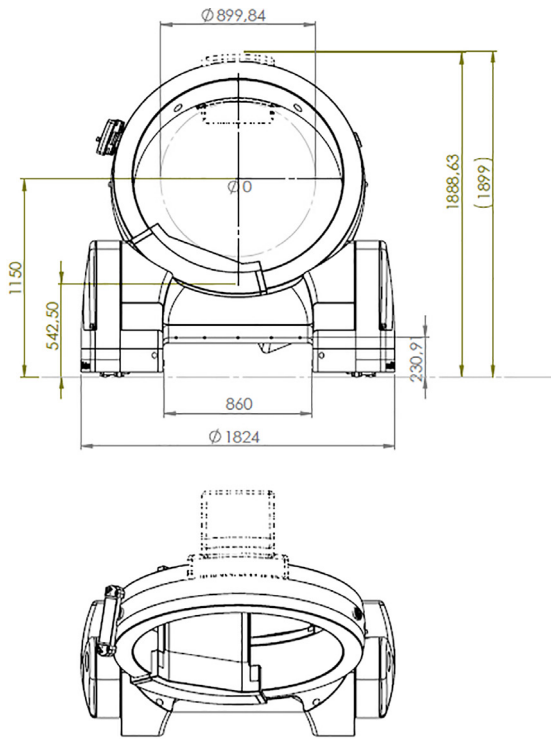
Industrial Computer	
<b>Processor</b>	Intel® Xeon® Processor E3-1275 v5 (8M Cache, 4.0 GHz)
<b>Memory</b>	32 GB ECC DDR4-2133
<b>Graphics</b>	NVIDIA® GeForce® RTX 2060 SUPER or newer (8 GB GPU RAM)
<b>Built in Storage</b>	5 TB HDD ( 1000 CBCT acquisitions) +256 GB internal SSD

Ports	
<b>Interfaces</b>	Ethernet – For navigation (length 5 m-) Ethernet – For hospital network (length 10 m) Ethernet – For WiFi extension (length 10 m) Power Supply (length 4m) PE (length 8m) 2x Multifunctional interfaces (refer IFU for more information)
<b>Network</b>	IEEE 802.3ab 1000BASE-T (internal) IEEE 802.11ac WiFi-5 1300 Mbps (HMI) IEEE 802.11n WiFi-4 450 Mbps (PACS)
<b>Input Voltage</b>	230 V +/- 10%, 50-60 Hz, 2 kVA (4 kVA Peak) 120 V +/- 10%, 50-60 Hz, 2 kVA (4 kVA Peak) Line Impedance ≤ 2 Ω @ 230 V/≤ 0.43 Ω @ 120 V
<b>Uninterruptable Power Supply</b>	✓ (optional, external 6000 W power capacity, 208/220/230/240 VAC output, 40–70 Hz, 16x 12V/7Ah batteries)
<b>Built-in Transformer</b>	✓ (optional, but max X-ray power will be limited to 1.56 kW on 120 V/13 A main supply.)

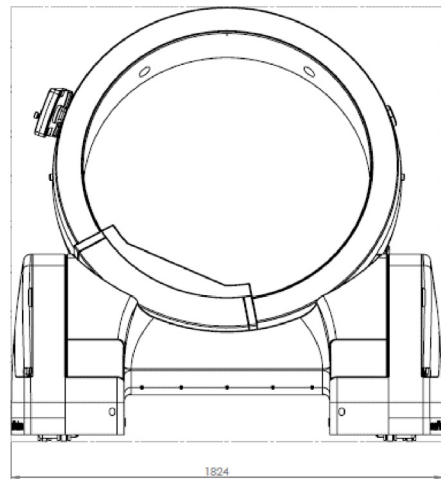
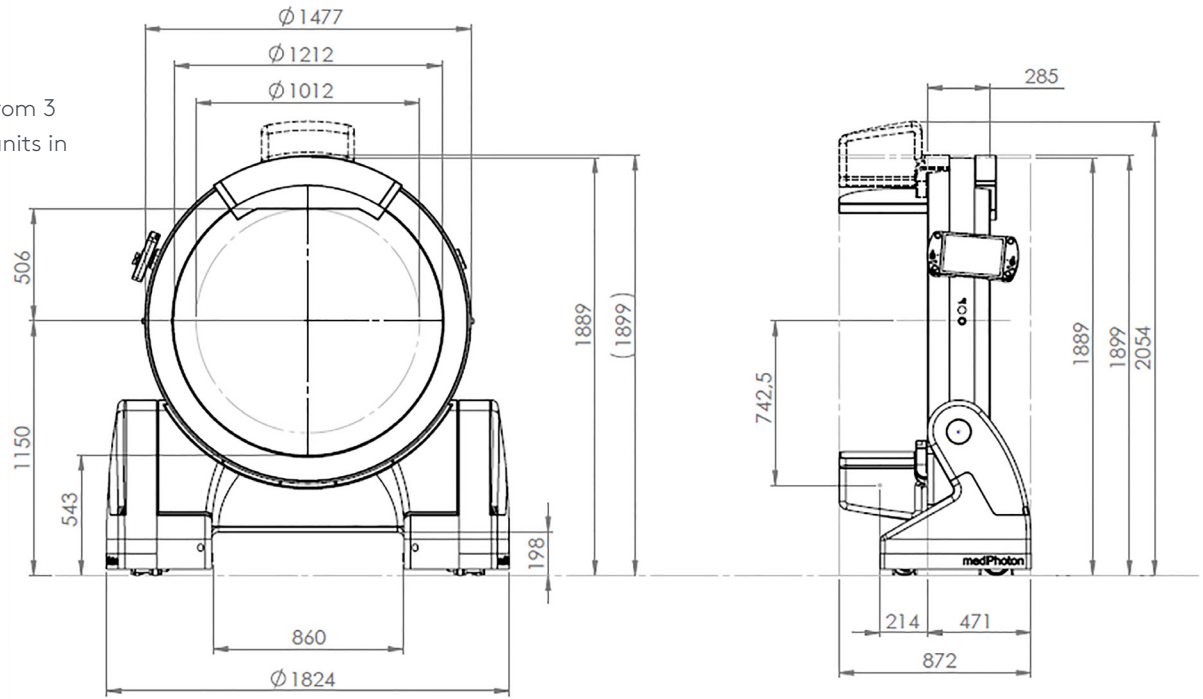
Physical Specifications	
<b>Total Weight</b>	517 kg (1139lbs) fully equipped with all options, excl. disconnected wireless controls
<b>Gantry Weight w/o Carrying Structure</b>	203 kg (447.54 lbs)
<b>Transformer Weight</b>	21.5 kg (47.4 lbs)
<b>Surface Load (Under Wheels)</b>	< 245 N/cm <sup>2</sup> (51169.3 lbf/sqft) in parking position
<b>Wheels (Diameter, Width, Hardness)</b>	4 x 125 mm, 40 mm, 75°A
<b>Minimum Space Requirement (Footprint)</b>	min. 1.59 m <sup>2</sup> (17.11 sqft) 2.6 m <sup>2</sup> (22.99 sqft) in parking position with margin required due to moving components
<b>Floor Pressure (weight / space required in parking position with additional space required for moving components)</b>	193.46 kg/m <sup>2</sup> (39.62 lbs/sqft)
<b>Dimensions (Width x Length x Height) [cm]</b>	182 x 87 x 189

Environmental Conditions	
<b>Temperature (Operation)</b>	15°C – 32°C
<b>Temperature (Storage)</b>	0°C - 40°C
<b>Temperature (Transport)</b>	-10°C - 50°C
<b>Relative Humidity (Operation)</b>	30% – 60% (no condensation)
<b>Relative Humidity (Storage)</b>	10% – 75% (no condensation)
<b>Relative Humidity (Transport)</b>	5% – 75% (no condensation)
<b>Air Pressure (Operation) [mbar]</b>	800 – 1100
<b>Air Pressure (Storage) [mbar]</b>	750 – 1100
<b>Air Pressure (Transport) [mbar]</b>	750 – 1100
<b>Peak Heat Output</b>	250 W Standby 1600 W during CBCT acquisition

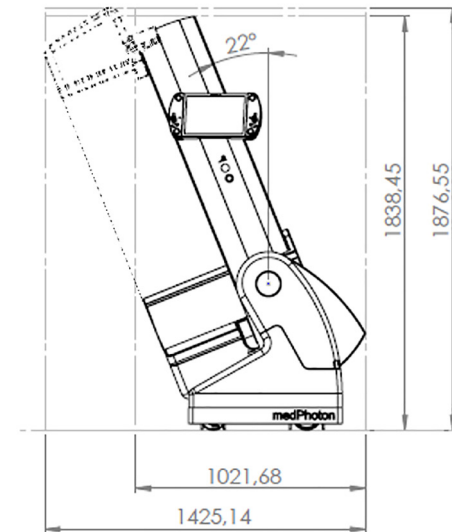
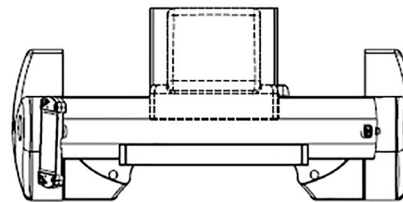
Accessories	
<b>RingPad (Human Machine Interface, HMI) - wireless control, handheld with joysticks to control motion of system and buttons to start/stop pre-planned motion and irradiation, with tablet Microsoft Surface Pro 7 touch screen</b>	✓ Microsoft Surface Pro 7 Display: 12,3" at 2736 x 1824 px (267 PPI) 10-Punkt-Multi-Touch Intel® Core™ i5-1035G4 Quad-Core Processor 16 GB LPDDR4x RAM 256 GB SSD
<b>Interfaces on RingPad (HMI)</b>	1 x USB-C (+ additional Hub to connect monitor and input devices)
<b>Wired Footswitch - with functions to acquire planar or fluoroscopic images</b>	✓ (optional)
<b>Wireless Footswitch</b>	✓ (optional)
<b>External Workstation - desktop PC with monitor, keyboard and mouse, storage, CPU and GPU graphics card performance sufficient for image acquisition and visualization tasks. PC can be used in a radiation protected area as a viewing console for images.</b>	✓ (optional)
<b>CC2 Control Console - wired control console with buttons to start / stop motion and exposures, including a wired safe emergency stop button - to be used in radiation protection areas in connection with the desktop PC</b>	✓ (optional)
<b>Cylinder Phantom for Flexmap Calibration - to be used by service engineers or physicists in system calibration or QA</b>	✓ (optional)
<b>Diagnostic Monitor - large flat screen with high contrast and resolution to display acquired images in a larger format, for image review</b>	✓ (optional)
<b>DICOM conformance</b>	✓
<b>PACS interfaces</b>	✓ wired (optional wireless)



**Figure 1.**  
IRm in parking  
position, shown from 3  
perspectives. All units in  
mm.



**Figure 2**  
IRm with 0° gantry tilt. All units in mm.



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ImagingRing-m may not yet be available in all markets.



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